



**CAN/CAN-Gateway**  
**CG-ARM7/RMD**  
**User Manual**

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User manual CG-ARM7/ RMD

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## Table of contents

<b>1</b>	<b>Overview . . . . .</b>	<b>1</b>
1.1	Features . . . . .	1
1.2	General description . . . . .	1
1.3	Ordering information . . . . .	1
<b>2</b>	<b>Handling . . . . .</b>	<b>2</b>
2.1	Connection . . . . .	2
2.2	Operation . . . . .	2
2.3	Configuration . . . . .	2
2.3.1	Configuration file . . . . .	3
2.3.2	Programming the device . . . . .	9
2.4	Display . . . . .	12
<b>3</b>	<b>Technical specifications. . . . .</b>	<b>14</b>
3.1	Pin assignment . . . . .	14
3.2	Limiting values . . . . .	15
3.3	Nominal values . . . . .	15
<b>4</b>	<b>Appendix . . . . .</b>	<b>16</b>
4.1	Configuration file sample . . . . .	16
4.2	Standard baudrates . . . . .	17

# 1 Overview

## 1.1 Features

- Connection of two physically separated CAN networks
- Filtering and mapping of identifiers
- Bus activity displayed by LED
- Gateway configuration via RS232 or CAN
- Wiring using a multiway connector

## 1.2 General description

The CAN/CAN gateway CG-ARM7 connects two physically divided CAN networks. The capability of having individual baudrates on both segments, enables routing between them.

The filtering of single identifiers or ranges of identifiers lessens the busload. The mapping of single or ranges of identifiers qualifies CG-ARM7 to be used under difficult higher level protocol conditions.

The device is configured via serial interface or via CAN network. Due to the intuitive structure of the configuration file in ASCII format, programming and administration is very easy.

## 1.3 Ordering information

12-20-401-10	CG-ARM7/RMD
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## 2 Handling

### 2.1 Connection

The CG-ARM7 possesses a multiway connector for flexible wiring of the CAN interfaces and the power supply. The RS232 interface on the device is used for programming and for the output of diagnostic information. For normal operation it is not required.

The connector assignment of the multiway connector and the RS232 interface is located in chapter "3.1 Pin assignment" in this manual or on your devices front panel.

### 2.2 Operation

To start up the gateway just connect the power supply, the device starts automatically. As soon as the automatic diagnostics is completed successfully, the green power LED lites up permantly.

**Important note:** Ex factory the device offers no configuration and must be configured before it is first run. Configuration instructions for the gateway are located in chapter "2.3 Configuration".

### 2.3 Configuration

The gateway configuration process consists of two steps:

- Creating a configuration file

- Storing the configuration file into the gateway

### 2.3.1 Configuration file

The configuration file is a text file with the extension \*.gcf. This file holds all data needed by the gateway for operation. A complete sample configuration is located in chapter “4.1 Configuration file”.

The values can either be entered in decimal or hexadecimal notation. Using the hexadecimal notation, put the character “x” directly before the particular value.

There are two types of parameters, general parameters and routing settings. General parameters include operating information for the gateway. Routing settings are used for mapping and filtering of identifiers.

Some parameters are optional. If they are not defined, the gateway uses default settings.

Simultaneous programming of several devices is not possible. It must be guaranteed, that each device can be clearly identified.

In the following all parameters are listed and described.

#		comment
---	--	---------

---

The configuration file can be provided with comments. Comments are prefaced with the character “#” and they end with the particular line.

**Example:**

```
# 1st comment  
key = value # 2nd comment
```

version	version
---------	---------

---

The gateway requires a version number to identify the programmed configuration. The version number for the CG-ARM7 standard version is 1. This key must exist in each configuration file.

**Important:** The version is not the version of the configuration! The version display what kind of configuration is be loaded!

**Example:**

```
version = 1
```

btr	bit timing
-----	------------

---

The bit timing key indicates the speed of the particular CAN channel. BTR1 indicates the baud rate for CAN channel 1, BTR2 the baud-rate for CAN channel 2. Both keys must exist in each configuration file.

This keys are directly related to the CANBTR registers of the used controller LPC2119. This allows most flexible customization of the baud-rate settings. The basic can clock is 48 MHz.

**Example:**

```
# CAN channel 1: 1Mbit/s  
btr1 = x00140005  
# CAN channel 2: 500KBit/s  
btr2 = x001C0005
```

Standard speeds recommend by CiA are located in chapter “4.2 Standard baudrates”.

pidin, pidout	program identifier
------------------	--------------------

The program identifiers (PIDs) are required for the gateway configuration via CAN. If you do not want to program the gateway via CAN, you can remove this keys from your configuration file.

The PIDs determine which identifiers will be used for programming the gateway. “pidin” defines the identifier the configuration software uses to send requests to the gateway. The key “pidout” defines the identifier which the gateway uses to reply to the configuration software.

For CAN channel 1 and CAN channel 2 different PIDs can be set. But it is also possible to program the gateway just via one CAN channel. To set the wanted identifiers for CAN channel 1 use the keys “pidin1” and “pidout1”. For CAN channel 2 use the keys “pidin2” and “pidout2”.

To use a 29-bit identifier prepend the character “x” before the particular key. Without prefix before the key 11-bit identifiers will be sent.

**Example:**

```
# PIDs for CAN channel 1
# CAN 1: 11-bit IN-Id: 0x5
pidin1 = x5
# CAN 1: 29-bit OUT-Id: 0xA00
xpidout1 = xA00
```



```
# PIDs for CAN channel 2
# CAN 2: 29-bit IN-Id: 0x6E
xpidin2 = x6E
# CAN 2: 29-bit OUT-Id: 0x1FFE
xpidout2 = x1FFE
```

name	configuration label
------	---------------------

---

For easier identification of the programmed settings, the configuration can be labeled. The configuration name must not have more than 32 characters and must not contain space characters or tabs. If this key is missing, no name will be assigned to the configuration.

**Example:**

```
name = standard_configuration
```

deviceid	device id
----------	-----------

---

During the configuration process via CAN the device has to be uniquely selected in the network. This process is based on the serial number of the device.

If there is the need to have the configuration process independent of the serial number, a device id can be assigned. Then the identification of the device depends on the device id and not on the serial number.

Care must be taken to use a particular device id just once in a network, if more than one gateways is used.

The device id can have values between 1 and 99999999.

**Example:**

```
deviceid = 50
```

---

`busoff` | bus off behavior

---

This key defines the period in milliseconds, which shall be waited until the gateway gets bus on again after a bus off condition has occurred. If this value is not defined, the device remains in bus off state. If a bus off time of 0 milliseconds is set, the gateway tries immediately to get bus on again.

**Example :**

```
busoff = 100
```

`password` | password

---

Using a password, the gateway can be protected against unauthorized access. If the key is not defined or the value is set to 0, password protection is disabled. The password is an up to 14-digit hexadecimal value.

The password protection supports two security levels.

For the highest security level the highest bit (56th bit) of the password must be set to 1. This security level prevents any communication with the gateway, if the device has not been unlocked with the correct password before. At the normal security level, the highest bit (56th bit) is 0. Read out of information about the gateway and the configuration is enabled. Changing the configuration however is not possible!

**Example:**

```
# Security: high
```

---

```
password = 80 07 05 AF D6 B0 D1
# Security: normal
password = 00 07 05 AF D6 B0 D1
```

fil	routing
-----	---------

---

The routing settings contain the filtering and mapping rules for a single identifier or ranges of identifiers. Only stated identifier or ranges of identifiers are transmitted and, if existent, the adequate mapping rule is applied. All incoming messages with identifiers to which no rule applies are ignored (defined program identifiers excepted). Additionally the frame format must be set within the filtering rules.

Key structure:

Different from the basic keys, the routing key is constructed in a more complex way. The key specifies 3 criteria:

```
[inff] fil channel [outff] =
...
```

1. *inff*: Defines the frame format for incoming messages.

The frame format for incoming messages specifies whether the filtering rule is applied to standard or extended messages. If *inff* is set to 's' standard frame format is specified. When set to 'x' the extended frame format is defined.

2. *channel*: Defines the channel number.

The channel number specifies whether the filtering rule is applied to incoming messages on CAN channel 1 or on CAN channel 2.

3. *outff*: Defines the frame format for outgoing messages.

The frame format for outgoing messages specifies whether the result of the filtering rule is sent via standard or extended identifier. If *outff* is set to 's' standard frame format is specified. When set to 'x' extended frame format is defined.

Structure of the filtering rule:

Now that the key defines to which message the rule applies, further selections have to be made. The filtering rule in turn specifies 3 criteria:

... = *sid* [- *eid*] [: *mid*]

1. *sid*: Defines the identifier the filtering rule is applied to.

If a range of identifiers is defined, *sid* is the start identifier. If the prefix 'x' is before the value the identifier is interpreted as a hexadecimal number.

2. *eid*: Defines the end identifier for ranges of identifiers.

If no range of identifiers is used, the value is not needed. If the prefix 'x' is before the value the identifier is interpreted as a hexadecimal number.

3. *mid*: Defines the mapping identifier.

The mapping identifier states the start identifier, to which the single identifier or the range of identifiers is mapped. Should the identifiers not be mapped it is not needed to set this value. If the prefix 'x' is before the value the identifier is interpreted as a hexadecimal number.

---

**Example:**

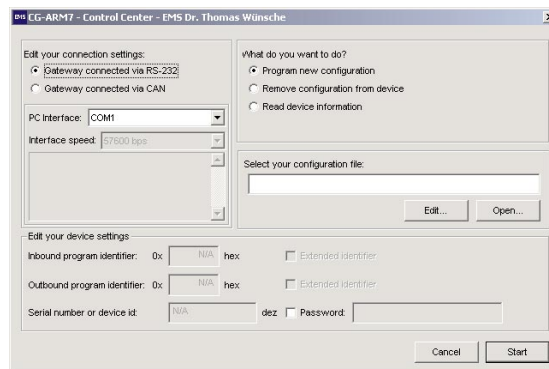
```
# The via CAN channel 1
# received extended
# identifiers in the range
# of 0x30 to 0x40 are
# sent via CAN channel 2
# as standard identifiers in
# the range of 0x400 to
# 0x410.
xfills = x30 - x40 : x400

# The via CAN channel 2
# received extended
# identifier 0x1FFFFFFF
# is sent via CAN channel 1
# as extended identifier
# with the value 0x01.
xfil2x = x1FFFFFFF : x1

# The via CAN channel 1
# received standard
# identifiers in the range
# of 0x100 to 0x200 are
# sent via CAN channel 2
# as standard identifiers
# in the range of 0x100
# to 0x200.
sfills = x100 - x200
```

**2.3.2 Programming the device**

CG-ARM7 is programmed by means of the configuration software. It offers the possibility to configure the gateway via serial connection or via CAN. For the configuration a serial cable or a PC-CAN interface of EMS Dr. Thomas Wuensche is needed.



### Setting up the PC interface:

The PC interface is set in the upper left field. First you choose, if the gateway shall be accessed via RS232 or via CAN interface. If the configuration software recognizes, that you do not use an interface of EMS Dr. Thomas Wunsche you can not select CAN as your interface.

Next the PC interface with which you want to connect to the CG-ARM7 has to be chosen. If you have selected RS232 as interface before, you set up the COM interface here. If you have chosen CAN, you select your CAN interface here.

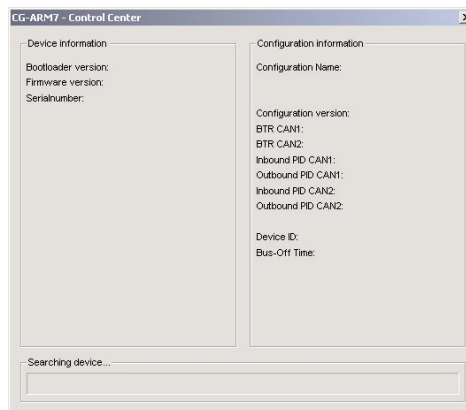
Speed can only be selected, when a connection via CAN has been made. Choose a standard baudrate compliant to the CiA or choose "Custom" to insert a user defined setting. Your selected baudrate must be the same as the baudrate of the gateway.

If no configuration is in the gateway it is not possible to communicate with the gateway via CAN.

**Process selection:**

In the right upper field of the configuration software you choose the process, you want to perform.

- **Program new configuration**  
With this process you can program a new configuration to the device. Before starting you have to select the configuration you want to write to the gateway.
- **Remove configuration from device**  
This process deletes the current configuration on the CG-ARM7. Afterwards the gateway is in delivery state again. It is not needed to delete the configuration before a new one is programmed, as this is done automatically.
- **Read device information**



Here information about the gateway and the configuration within can be read out.

**Optional device settings**

If the CG-ARM7 is password protected, you must activate the field “password” and fill in the correct password. Depending on the security level, it is possible to request information about the device even without password.

If CAN has been chosen as the PC interface the “Inbound Program Identifier” (pidin), the “Outbound Program Identifier” (pidout) and the frame format for the program identifiers have to be set. At last the serial number or the configured device id of the device has to be inscribed for explicit identification. If you use only one gateway in the network, you can also inscribe the value ‘0’ here. Never use the value ‘0’, if there are more than one CG-ARM7 gateways in the network.

**Starting the download:**

To start the download process press start. The operation may take a while, do not disconnect the power supply to the device during the configuration process. At that time the routing functionality of the gateway is deactivated. After successful completion no status message is displayed. If an error occurs a status message is displayed.

## 2.4 Display

The device status is displayed by three LEDs.

**Power**

On	The device is in normal operation mode. Routing of CAN messages is enabled.
----	---

---



Blinking	The device is in programming mode. Routing of CAN messages is disabled.
----------	--

**CAN 1 Active**

On	There is bus activity on CAN 1.
----	---------------------------------

**CAN 2 Active**

On	There is bus activity on CAN 2.
----	---------------------------------

### 3 Technical Data

#### 3.1 Pin assignment

##### Pin assignment of the multiway connector

Pin	Signal	Description
1	+24V	+24 Volt power supply
2	GND	Ground*
3	GND	Ground*
4	CAN1-H	CAN1-High Buswire
5	CAN1-L	CAN1-Low Buswire
6	GND	Ground*
7	CAN2-H	CAN2-High Buswire
8	CAN2-L	CAN2-Low Buswire

\* Internal connected

##### Pin assignment RS232

Pin	Signal	Description
1		not connected
2	RxD	Receive signal
3	TxD	Transmit signal
4		not connected
5	GND	Ground
6		not connected
7	RTS	not used
8	CTS	not used
9		not connected

### 3.2 Limiting values

Stresses above the specified values can lead to permanent damage of the CG-ARM7.

Parameter	Min.	Max.	Unit
Storage temperature	-20	80	C
Operating temperature	0	60	C
Supply voltage	-100	30	V

**Note:** With respect to methods of measurement it is not possible to have ESD protection circuits at the CAN terminals. ESD protection on this terminals is determined by the ESD capability of the used CAN transceiver (Philips 82C251).

### 3.3 Nominal values

Parameter	Min.	Max.	Unit
Supply voltage	10	30	V
Baudrates	10	1000	kBit/s

## 4 Appendix

### 4.1 Configuration file example

```
# Gateway CG-ARM7/RMD configuration file

# Baudrate CAN interface 1 - 1000 kbps
btr1=x00140005

# Baudrate CAN interface 2 - 500 kbps
btr2=x001C0005

# Version number of configuration file
version=1

# Device ID
deviceid=120000

# Set bus off recovery time to 1000 ms
busoff=1000

# Password protection: security level
# normal
password=11 AA 33 BC

# Configuration name
name=router

# Program identifier CAN channel 1
pidin1=x1      # Standard identifier 0x01
xpidout1=x2    # Extended identifier 0x02

# Program identifier CAN channel 2
xpidin2=x10    # Extended identifier 0x10
xpidout2=x20   # Extended identifier 0x20

# Filter settings
```

```

# All standard identifiers from CAN channel
# 1 are sent as standard identifiers to CAN
# channel 2
sfill1s=x0-x7FF

# All standard identifiers from CAN channel
# 2 are sent as standard identifiers to CAN
# channel 1
sfil2s=x0-x7FF

# All extended identifiers from CAN channel
# 1 are sent as extended identifiers to CAN
# channel 2
xfill1x=x0-x1FFFFFFF

# All extended identifiers from CAN channel
# 2 are sent as extended identifiers to CAN
# channel 1
xfil2x=x0-x1FFFFFFF

```

## 4.2 Standard baudrates

### Speeds recommended by CIA:

Baudrate	Bit Timing Register
1000 kbps	0x00140005
800 kbps	0x00160005
500 kbps	0x001C0005
250 kbps	0x001C000B
125 kbps	0x001C0017
100 kbps	0x001C001D
50 kbps	0x001C003B
20 kbps	0x001C0095
10 kbps	0x001C012B

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